### Validation Report

### Virginia, SPS-1 Task Order 16, CLIN 2 January 30 to February 1, 2007

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### 1 Executive Summary

A visit was made to the Virginia 0100 on January 30 to February 1, 2007 for the purposes of conducting a validation of the WIM system located approximately 8 miles north of Danville on the US-29 Bypass. The SPS-1 is located in the righthand, southbound lane of a four-lane divided facility. The LTPP lane is one of 2 lanes instrumented at this site. This report discusses the validation of the LTPP lane. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This is the first validation visit to this location. The site was installed November 1 to 4, 2006, and was subsequently calibrated by International Road Dynamics/PAT Traffic. This site is located approximately 500 feet downstream from a previous location.

This site meets all LTPP precision requirements except speed which is not considered sufficient to disqualify the site as having research quality data. The classification data is of research quality.

The site is instrumented in both lanes with bending plate WIM sensors and an IRD/PAT Traffic iSINC controller. It is installed in a section of portland cement concrete that is 424 feet long. The WIM sensors are 313 feet from the asphalt to concrete pavement transition. The LTPP Lane is designated as Lane number 1 by the controller.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 75,750 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having air suspension and a trailer with standard rear tandem and tapered leaf/walking beam suspension loaded to 65,310 lbs., the "partial" truck.

The validation speeds ranged from 42 to 65 miles per hour. The pavement temperatures ranged from 27 to 45 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was not achieved.

Table 1-1 Post-Validation results – 510100 – 31-Jan-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$-4.7 \pm 5.4\%$	Pass
Tandem axles	±15 percent	$-0.1 \pm 7.2\%$	Pass
GVW	±10 percent	$-0.8 \pm 5.5\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	$0.1 \pm 1.4 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0 \pm 0.1 \text{ ft}$	Pass

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions

significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area. Discernable bouncing that was observed at the point of the pavement transition 313 feet prior to the scale area appeared to diminish prior to the trucks traversing the WIM scales.

Profile data collected since the site installation does not exist. To our knowledge a site visit to collect profile data has not yet been scheduled. An amended report will be submitted when the profile data is available.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 Results Based on ASTM E-1318-02 Test Procedures

	Limits for Allowable	Percent within	
Characteristic	Error	Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

This site needs 5 years of data to meet the goal of five years of research quality data.

### 2 Corrective Actions Recommended

The loop lead-ins should be replaced from the pull box to the cabinet with shielded two-conductor wire to provide grounding and shielding and prevent cross-talking between the loops. This correction is to address a problem currently existing in the adjacent lane.

### 3 Post Calibration Analysis

This final analysis is based on test runs conducted January 31, 2007 during the afternoon hours and continuing on February 1, 2007 during the morning hours at test site 510100 on the US-29 Bypass. This SPS-1 site is at milepost 12.8 on the southbound, righthand lane of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for the validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 75,750 lbs., the "golden" truck
- 2. 5-axle tractor semi-trailer with a tractor having air suspension and a trailer with standard rear tandem and tapered leaf/walking beam suspension loaded to 65,310 lbs., the partial truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 42 to 65 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 27 to 45 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

As shown in Table 3-1, this site meets all LTPP precision requirements except speed which is not considered sufficient to disqualify the site as having research quality data.

Table 3-1 Post-Validation Results – 510100 – 31-Jan-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence Site Values		Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$-4.7 \pm 5.4\%$	Pass
Tandem axles	±15 percent	$-0.1 \pm 7.2\%$	Pass
GVW	±10 percent	$-0.8 \pm 5.5\%$	Pass
Speed	$\pm 1 \text{ mph } [2 \text{ km/hr}]$	$0.1 \pm 1.4 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

The test runs were conducted primarily during the afternoon hours of January 31<sup>st</sup> and the morning hours of February 1<sup>st</sup>, 2007. Temperatures over the course of the test period did not fluctuate by a considerable amount, resulting in a modest range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and two temperature groups. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the

desired distribution of speed and temperature combinations was not achieved for this set of validation runs.

The three speed groups were divided as follows: Low speed -42 to 48 mph, Medium speed -49 to 57 mph and High speed -58+ mph. The two temperature groups were created by splitting the runs between those at 27 to 34 degrees Fahrenheit for Low temperature, and 35 to 45 degrees Fahrenheit for High temperature.

## Speed versus Temperature Combinations 70 65 60 40 40 45 50

Figure~3-1~Post-Validation~Speed-Temperature~Distribution-510100-31-Jan-2007

Temperature (F)

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance. Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. From the figure, it appears that the equipment estimates GVW fairly accurately at all speeds. There appears to be more variability in error at the medium speeds when compared with low and high speeds.

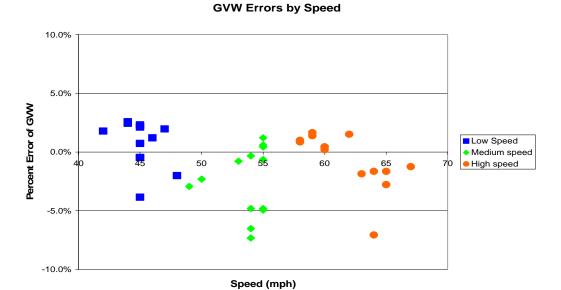


Figure 3-2 Post-validation GVW Percent Error vs. Speed – 510100 – 31-Jan-2007

Figure 3-3 shows the lack of relationship between temperature and GVW percentage error.

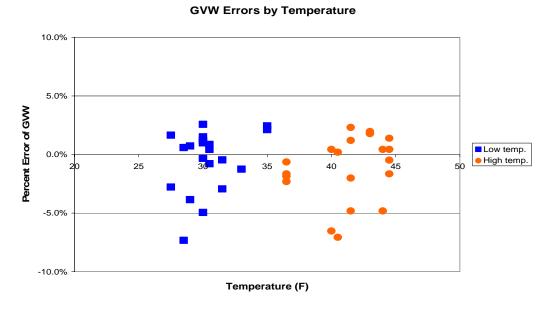


Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 510100 – 31-Jan-2007

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the

drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. The graph indicates that the errors in tandem spacings for the test trucks were not affected by changes in speed.

### Drive Tandem Spacing vs. Radar Speed 0.12 0.09 0.06 Spacing error (ft) 0.03 Speed/space 45 55 60 65 -0.03 -0.06 -0.09 -0.12 Speed (mph)

### Figure 3-4 Post-Validation Spacing vs. Speed – 510100 – 31-Jan-2007

### 3.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 27 to 34 degrees Fahrenheit for Low temperature, and 35 to 45 degrees Fahrenheit for High temperature.

**Table 3-2 Post-Validation Results by Temperature Bin – 510100 – 31-Jan-2007** 

Element	95% Limit	Low Temperature 27 to 34 °F	High Temperature 35 to 45 °F
Steering axles	<u>+</u> 20 %	-4.3 ± 6%	$-5.2 \pm 5.1\%$
Tandem axles	<u>+</u> 15 %	$0.2 \pm 7.2\%$	$-0.4 \pm 7.4\%$
GVW	<u>+</u> 10 %	$-0.5 \pm 5.5\%$	$-1.2 \pm 5.8\%$
Speed	<u>+</u> 1 mph	$0.3 \pm 1.5 \text{ mph}$	$0.0 \pm 1.4 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

From Table 3-2, it appears that the equipment underestimates GVW and steering axle weights at all temperatures. For tandem axle weights, the equipment slightly overestimates at the lower temperatures and slightly underestimates at the higher temperatures. The variability in error for all weights appears to remain constant over the course of the entire temperature range.

As shown in the following figures, the temperature related trends observed during the pre-validation do not appear in the post-validation results.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph. From the figure it can be seen that GVW for both trucks is underestimated at all temperatures. Variability in error is higher at the low and high ends of the temperature range.

## 10.0% 5.0% 0.0% 20 25 30 35 40 45 50 Partial

### **GVW Errors vs. Temperature by Truck**

Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 510100 – 31-Jan-2007

Temperature (F)

Figure 3-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

From the figure, it can be seen that the equipment underestimates steering axle weights at all temperatures. Variability in error is fairly consistent over the entire temperature range. As shown in figure, the temperature related trends on steering axle weights observed during the pre-validation do not appear in the post-validation results. This may be the result of the limited sample size at these temperatures.

### Steering Axle Errors vs. Temperature

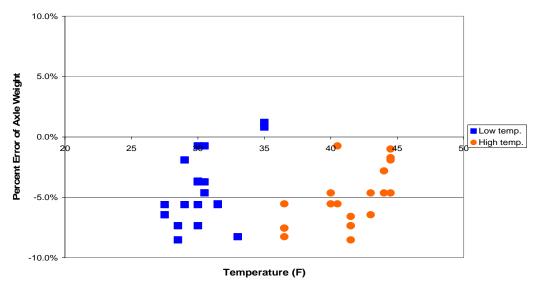


Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group – 510100 – 31-Jan-2007

### 3.2 Speed-based Analysis

The three speed groups were divided using 42 to 48 mph for Low speed, 49 to 57 mph for Medium speed and 58+ mph for High speed.

Table 3-3 Post-Validation Results by Speed Bin – 510100 – 31-Jan-2007

Element	95% Limit	Low Speed 42 to 48 mph	Medium Speed 49 to 57 mph	High Speed 58+ mph
Steering axles	<u>+</u> 20 %	$-4.1 \pm 6.4\%$	$-6 \pm 3.9\%$	-4.3 ± 6%
Tandem axles	<u>+</u> 15 %	$1.0 \pm 6.7\%$	$-1.4 \pm 9.1\%$	$0.1 \pm 5.7\%$
GVW	<u>+</u> 10 %	$0.3 \pm 5.4\%$	$-2.1 \pm 6.3\%$	$-0.6 \pm 5.1\%$
Speed	<u>+</u> 1 mph	$0.3 \pm 1.4 \text{ mph}$	$0.0 \pm 1.2 \text{ mph}$	$0.0 \pm 1.8 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

From Table 3-3, it can be seen that the equipment underestimates steering axle weights at all speeds. For tandem weights, the equipment underestimates at low and high speeds and underestimates at medium speeds. GVW weights are overestimated at low speeds and are underestimated at medium and high speeds. Variability in steering axle errors is lower at medium speeds when compared to low and high speeds. For tandem axles, variability is higher at medium speeds when compared with low and high speeds. GVW error variability is fairly consistent over the entire speed range.

Figure 3-7 illustrates the tendency for the equipment to overestimate GVW at low speeds and underestimate at medium and high speeds for the population as a whole. For the Golden truck, the equipment estimates GVW reasonably well at low and high speeds and underestimates GVW at the medium speeds. Variability is fairly constant over the entire

speed range for the population as a whole as well as for each truck individually. Speed data studies conducted from post-visit data have indicated that the 15<sup>th</sup> percentile speed at this site is 58 mph. This is the low end of the High speed range for this validation.

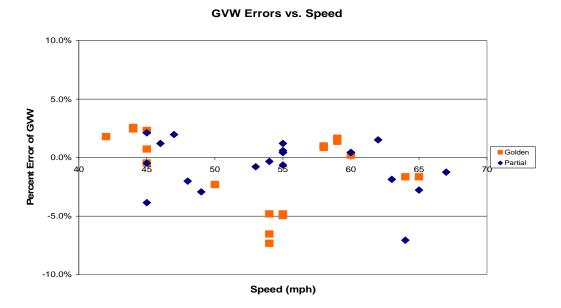
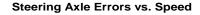


Figure 3-7 Post-Validation GVW Percent Error vs. Speed by Truck-510100-31-Jan-2007

Figure 3-8 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

The figure illustrates how the WIM equipment underestimates steering axle weights at all speeds. The variability in error appears to remain constant over the entire speed range.



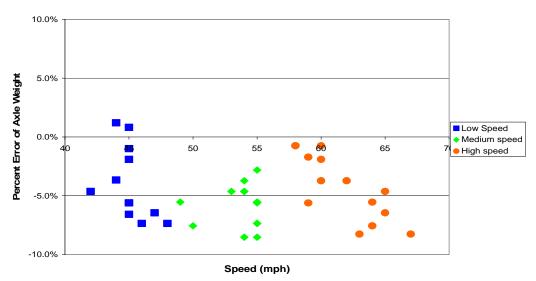


Figure 3-8 Post-Validation Steering Axle Percent Error vs. Speed by Group – 510100 – 31-Jan-2007

### 3.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to account for unclassified vehicles.

A post-validation classification validation was not performed since the results of the prevalidation classification and speed study indicated less than 2 percent misclassifications and less than 2 percent unknown vehicles. No changes to the equipment operational parameters were performed between the pre- and post-validation tests.

### 3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-4 Results of Validation Using ASTM E-1318-02 Criteria

	Limits for Allowable	Percent within	
Characteristic	Error	Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

### **4 Pavement Discussion**

The pavement condition did not appear to influence truck movement across the sensors.

### 4.1 Profile Analysis

Profile data collected since the site installation does not exist. A site visit to collect profile data has not been scheduled yet. An amended report will be submitted when the data is available.

### 4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement, discernable bouncing by trucks was observed at the transition point shown in Figure 4-1. It is located approximately 313 feet prior to the WIM scale area. Although not visible to the naked eye, a dip in the pavement at this location may be the cause. The effects of the distress on the dynamics of the trucks appear to diminish prior to the trucks entering the WIM scale area.



Figure 4-1 - Distress at Pavement Transition

### 4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires of any of the sensors for the equipment. There is discernable bouncing by trucks at the point of the asphalt to concrete transition 313 feet prior to the WIM scale area. These dynamics appear to diminish before the trucks enter the scale area.

### **5 Equipment Discussion**

The traffic monitoring equipment at this location includes bending plate sensors and an iSINC controller. These sensors are installed in a portland cement concrete pavement about 424 ft in length. The roadway outside this short section is asphalt.

### 5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. The loops sensor input leads were not shielded or grounded although they appeared to be working properly prior to beginning test truck runs. All sensors and system components were found to be within operating parameters.

### 5.2 Calibration Process

The equipment required no iterations of the calibration process between the initial 40 runs and the final 40 runs.

### 5.3 Summary of Traffic Sheet 16s

This site has validation information from the current visit only in the tables below. Table 5-1 has the information that should be found in TRF\_CALIBRATION\_AVC for Sheet 16s submitted for this validation.

**Table 5-1 Classification Validation History – 510100 – 31-Jan-2007** 

Date	Method	<b>Mean Difference</b>			Percent	
		Class 9 Class 8 Other 1 Other 2			Unclassified	
30-Jan-07	Manual	0	0			0.0

Table 5-2 has the information that will be found in TRF\_CALIBRATION\_WIM for Sheet 16s submitted for this validation.

Table 5-2 Weight Validation History – 510100 – 31-Jan-2007

Date	Method	Mean Error and (SD)		
		GVW	Single Axles	Tandem Axles
31-Jan-07	Test Trucks	-0.8 (2.7)	-4.7 (2.6)	-0.1 (3.6)
30-Jan-07	Test Trucks	0.7 (2.7)	-2.6 (3.2)	1.3 (3.5)

### 5.4 Projected Maintenance/Replacement Requirements

Semi-annual preventive maintenance is to be performed at this site under provisions of the Phase II contract.

Currently, the loop lead-ins need to be replaced with shielded two-conductor cable from the pull boxes to prevent cross-talk and errant and false vehicle reports. This is needed to correct a problem in the adjacent lane.

No other corrective maintenance actions required at this site at this time.

### **6 Pre-Validation Analysis**

This pre-validation analysis is based on test runs conducted January 30, 2007 during the early morning to mid afternoon hours at 510100 located approximately 8 miles north of Danville. This SPS-1 site is at milepost 12.8 on the US-29 Bypass in the southbound, righthand lane of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 75,710 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having air suspension and a trailer with standard rear tandem and tapered leaf/walking beam suspension loaded to 65,210 lbs., the "partial" truck.

For the initial validation each truck made a total of 21 passes over the WIM scale at speeds ranging from approximately 42 to 64 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 28 to 50 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-1.

As shown in Table 6-1, this site meets all LTPP precision requirements except speed which is not considered sufficient to disqualify the site as having research quality data.

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$-2.6 \pm 6.4\%$	Pass
Tandem axles	±15 percent	$1.3 \pm 6.9\%$	Pass
GVW	±10 percent	$0.7 \pm 5.4\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	$0.1 \pm 1.4 \text{ mph}$	Fail
Axle spacing	+ 0.5 ft [150mm]	$0.0 \pm 0.0 \text{ ft}$	Pass

**Table 6-1 Pre-Validation Results – 510100 – 30-Jan-2007** 

The test runs were conducted primarily during the afternoon hours of January 31<sup>st</sup> and the morning hours of February 1, 2007. Temperatures over the course of the test period did not fluctuate by a considerable amount, resulting in a narrow range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and two temperature groups. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was not achieved for this set of validation runs.

The three speed groups were divided into 42 to 48 mph for Low speed, 49 to 57 mph for Medium speed and 58+ mph for High speed. The two temperature groups were created

by splitting the runs between those at 28 to 40 degrees Fahrenheit for Low temperature, and 41 to 50 degrees Fahrenheit for High temperature. It can be seed from the figure that medium and high speed runs at the low end of the temperature range were not obtained.

## Speed versus Temperature Combinations

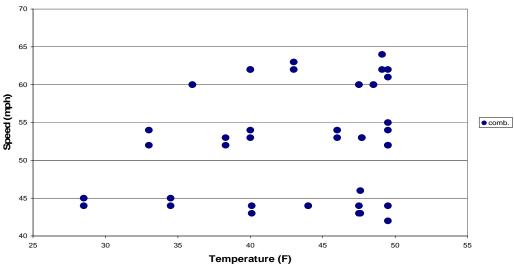


Figure 6-1 Pre-Validation Speed-Temperature Distribution – 510100 – 30-Jan-2007

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. The figure illustrates the tendency for the equipment to overestimate GVW at low and high speeds and underestimate GVW at medium speeds. Variability in error appears to greater at medium speeds when compared with low and high speeds.



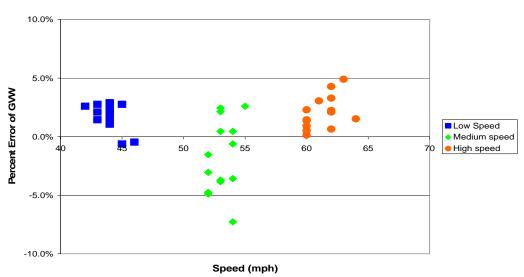


Figure 6-2 Pre-validation GVW Percent Error vs. Speed – 510100 – 30-Jan-2007

Figure 6-3 shows the relationship between temperature and GVW percentage error. It appears that the equipment estimates GVW reasonably well at all temperatures. Variability in GVW error appears to be fairly consistent over the entire temperature range, with a slight decrease at the high end of the temperature range due to one outlier.

## GVW Errors by Temperature

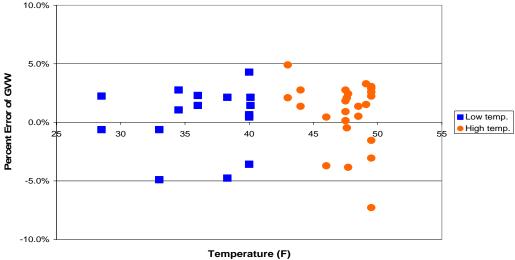


Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 510100 - 30-Jan-2007

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to

correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. The graph indicates that the errors in tandem spacings for the test trucks were not affected by changes in speed.

### 

### Figure 6-4 Pre-Validation Spacing vs. Speed - 510100 - 30-Jan-2007

### 6.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 28 to 40 degrees Fahrenheit for Low temperature, and 41 to 50 degrees Fahrenheit for High temperature.

Table 6-2 Pre-Validation Results by Temperature Bin – 510100 – 30-Jan-2007

Element	95% Limit	Low Temperature 28 to 40 °F	High Temperature 41 to 50 °F
Steering axles	<u>+</u> 20 %	$-1.8 \pm 5.9\%$	$-3.1 \pm 6.9\%$
Tandem axles	<u>+</u> 15 %	$0.9 \pm 6.9\%$	$1.6 \pm 7.2\%$
GVW	<u>+</u> 10 %	$0.4 \pm 5.7\%$	$0.8 \pm 5.6\%$
Speed	<u>+</u> 1 mph	$0.2 \pm 1.2 \text{ mph}$	$0.0 \pm 1.6 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

From Table 6-2, it appears that the equipment underestimates steering axle weights at all temperatures, and slightly overestimates tandem axle weights and GVW at all temperatures. The variability in error appears to remain fairly consistent over the entire temperature range for all weights.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck.

The equipment appears to estimate GVW reasonably well for the population as a whole. Individually, GVW for the "partial" truck (diamonds) is overestimated while GVW for the "golden" truck (squares) is estimated with reasonable accuracy. Variability in error for the golden truck appears to be greater than GVW error for the partial truck at all temperatures.

### **GVW Errors vs. Temperature by Truck**

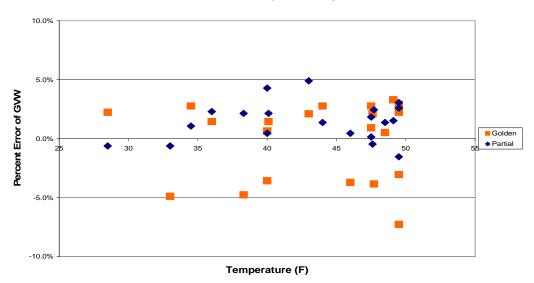


Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 510100 – 30-Jan-2007

Figure 6-6 shows the relation between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. The figure shows that steering axle weights are consistently underestimated by the equipment over the entire temperature range. Variability in error appears to be greater at the limits of the temperature range when compared to the median temperatures. This may be the result of the limited sample size at these temperatures. Post-validation runs were specifically performed at these temperatures to further investigate this trend.

### Steering Axle Errors vs. Temperature

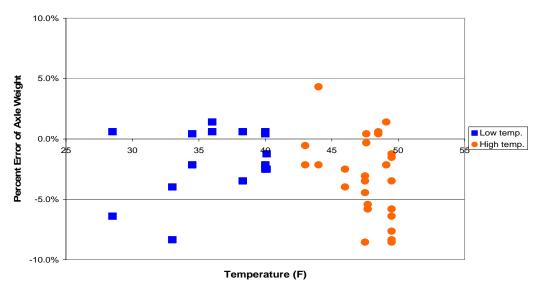


Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 510100 – 30-Jan-2007

### 6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -42 to 48 mph, Medium speed -49 to 57 mph and High speed -58+ mph.

Table 6-3 Pre-Validation Results by Speed Bin – 510100 – 30-Jan-2007

Element	95% Limit	Low Speed 42 to 48 mph	Medium Speed 49 to 57 mph	High Speed 58+ mph
Steering axles	<u>+</u> 20 %	$-2.6 \pm 8.1\%$	$-4.4 \pm 5.9\%$	$-0.8 \pm 3.9\%$
Tandem axles	<u>+</u> 15 %	$2.6 \pm 4.7\%$	$-1.2 \pm 8.4\%$	$2.5 \pm 4.9\%$
GVW	<u>+</u> 10 %	$1.8 \pm 2.5\%$	$-1.8 \pm 6.7\%$	$2.1 \pm 3.1\%$
Speed	<u>+</u> 1 mph	$0.4 \pm 1.4 \text{ mph}$	$-0.1 \pm 1.3 \text{ mph}$	$-0.1 \pm 1.6 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

From Table 6-3, it can be seen that the equipment underestimates steering axle weights at all speeds, and GVW and tandem weights at medium speeds. GVW and tandem weights are overestimated at low and high speeds. Variability in steering axle error appears to decrease as speed increases while the error spread for GVW and tandem weights is higher at medium speeds when compared to low and high speeds.

Figure 6-7 illustrates the tendency of the equipment to overestimate GVW at low and high speeds, and underestimate GVW at medium speeds for the population as a whole. For the "partial" truck (diamonds) GVW is estimated fairly consistent over the entire speed range, with a slight overestimation at the higher speeds. Variability for each truck individually is reasonably consistent over the entire speed range, however, the increased variability and the underestimation by the equipment for the population as a whole at the

medium speeds is driven by the considerably greater underestimation of GVW for the "golden" truck (squares) at these speeds.

Speed studies performed from the post-visit data download indicate that the 15<sup>th</sup> percentile for speed at this site is 58 mph, which indicates that the majority of trucks at this site are not affected by this trend. The 85<sup>th</sup> percentile speed at this site is 67 mph, which exceeds the speed limit and the capabilities of these tests. The graph indicates that GVW for trucks traveling at and above this speed may be overestimated similarly to those at the higher test speeds.

# Speed (mph)

Figure 6-7 Pre-Validation GVW Percent Error vs. Speed Group - 510100 -30-Jan-2007

Figure 6-8 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

From the figure, it appears that the equipment underestimates steering axle weights at all speeds. The underestimation appears to be greater at the low and medium speeds when compared with the higher speeds. Variability in error appears to also be greater at the low and medium speeds.

### Steering Axle Errors vs. Speed

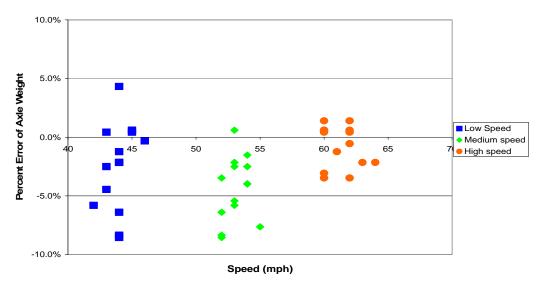


Figure 6-8 Pre-Validation Steering Axle Percent Error vs. Speed Group - 510100 – 30-Jan-2007

### 6.3 Classification Validation

This LTPP installed site uses the FHWA 13-bin classification scheme and the LTPP ETG mod 3 classification algorithm. Classification 15 has been added to account for unclassified vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on a 100 percent sample it was determined that there are 0 percent unknown vehicles and 0 percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-4 has the classification error rates by class. The overall misclassification rate is 0 percent.

Table 6-4 Truck Misclassification Percentages for 510100 – 30-Jan-2007

Class	Percent	Class	Percent	Class	Percent
	Error		Error		Error
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	N/A	13	N/A

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations

with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-5 Truck Classification Mean Differences for 510100 – 30-Jan-2007

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	N/A	5	0	6	0
7	N/A				
8	0	9	0	10	N/A
11	0	12	N/A	13	N/A

These error rates are normalized to represent how many vehicles of the class are expected to be over- or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

### 6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-6 Results of Validation Using ASTM E-1318-02 Criteria

	Limits for Allowable	Percent within	
Characteristic	Error	Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

### 7 Data Availability and Quality

As of January 30, 2007 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration

information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

This site is a new installation. The site was selected by IRD and is located approximately 500 feet downstream of the original site. Therefore, there is no data for this site. An additional 5 years of data is needed to meet the goal of a minimum of 5 years of research weight data.

The amount and coverage for the previous site is shown in Table 7-1. The value for months is a measure of the seasonal variation in the data. The indicator of coverage indicates whether day of week variation has been accounted for on an annual basis. As can be seen from the table only 1997 has a sufficient quantity to be considered a complete year of data. In the absence of previously gathered validation information it can be seen that at least 5 additional years of research quality data are needed to meet the goal of a minimum of 5 years of research weight data.

Table 7-1 Amount of Traffic Data Available 510100 – 30-Jan-2007

Year	Classification	Months	Coverage	Weight	Months	Coverage
	Days			Days		
1997	296	12	Full Week	286	11	Full Week
2004	7	1	Full Week			
2005	7	1	Full Week			

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Class 9s and Class 5s constitute more than 10 percent of the truck population. Based on the data collected from the end of the validation the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the RSC on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-2 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-2 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.

- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.
- o For all other trucks the typical axle configuration is used to determine the maximum allowable weight based on 18,000 pounds for single axles and 34,000 pounds for tandem axles. A ten percent cushion above that maximum is used to set the overweight threshold.
- o For all other trucks in the absence of site specific information the computation of under weights assumes the power unit weighs 10,000 pounds and each axle on a trailer 5,000 pounds. Ninety percent of the total for the unloaded configuration is the value below which a truck is considered under weight.
- o For all trucks other than class 9s that have a bi-modal distribution the unloaded peak is defined to be in a bin less than or equal to half of the allowable maximum weight.
- o For all trucks other than class 9s that have a bi-modal distribution the loaded peak is defined to be in a bin greater than or equal to half of the allowable maximum weight.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

Table 7-2 GVW Characteristics of Major sub-groups of Trucks – 510100 – 31-Jan-2007

Characteristic	Class 9	Class 5
Percentage Overweights	0.4%	0.5%
Percentage Underweights	0.0%	0.0%
Unloaded Peak	36,000 lbs	
Loaded Peak	84,000 lbs	
Peak		12,000 lbs

The expected percentage of unclassified vehicles is 2.0%. This is based on the percentage of unclassified vehicles in the post-validation data download.

The graphical screening comparison figures are found in Figure 7-1 through Figure 7-4. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the post-validation Sheet 16.

### **Class 9 GVW Distribution**

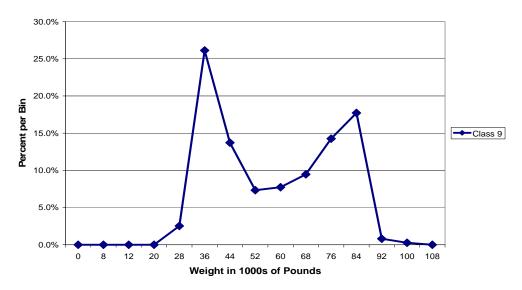


Figure 7-1 Expected GVW Distribution Class 9 – 510100 – 31-Jan-2007

### **Class 5 GVW Distribution**

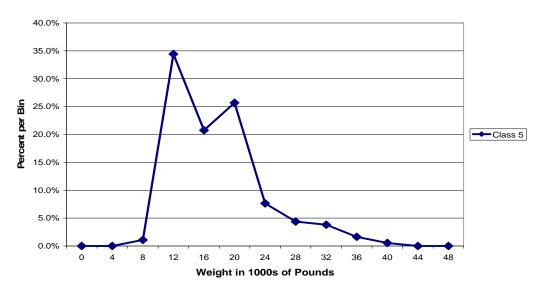


Figure 7-2 Expected GVW Distribution Class 5 – 510100 – 31-Jan-2007

### **Vehicle Distribution Trucks (4-15)**

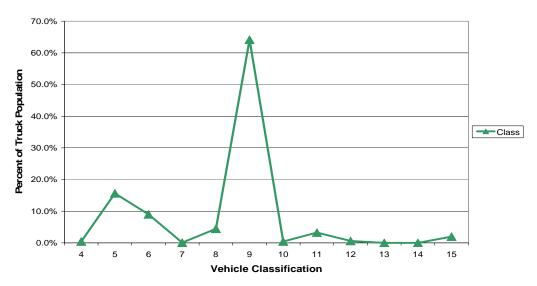


Figure 7-3 Expected Vehicle Distribution – 510100 – 31-Jan-2007

## Speed Distribution for Trucks

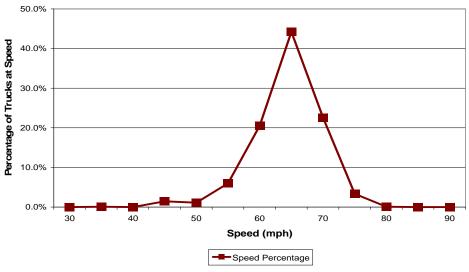


Figure 7-4 Expected Speed Distribution – 510100 – 31-Jan-2007

### 8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

Sheet 19 - Truck 1 - 3S2 loaded air suspension (4 pages) Sheet 19 - Truck 2 - 3S2 partially loaded air suspension tractor, tapered

leaf/walking beam suspension trailer (4 pages)

Sheet 20 – Speed and Classification verification Pre-Validation (2 pages)

Sheet 21 – Pre-Validation (3 pages)

Sheet 21 – Post-Validation (3 pages)

Sheet 22 – Site Equipment Assessment (8 pages)

Sheet 23 – WIM System Troubleshooting Outline (5 pages)

System Parameters (1 page)

Installed Class Scheme (1 page)

Truck Photographs (7 pages)

### 9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following this page. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

### 10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

### 11 Traffic Sheet 16(s)

Sheet 16s for the pre-validation and post-validation conditions are attached following the current Sheet 18 information at the very end of the report.

## POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

**STATE: Virginia** 

**SHRP ID: 510100** 

1.	General Information	. 3
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3.	Agenda	. 3
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5.	Truck Route Information	. 5
6.	Sheet 17 – Virginia (510100)	. 7

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Figure 5-2 – Truck Route at 510100 in Virginia
Figure 6-1 - Site Equipment Layout for 510100 in Virginia
Figure 6-2 - Site Map for 510100 in Virginia
Figure 6-3 – 6420060018_SPSWIM_TO_16_51_2.75_0100_Downstream _01_30_07.jpg
Figure 6-4 – 6420060018_SPSWIM_TO_16_51_2.75_0100_Upstream_01_30_07.jpg 11
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_01_30_07.jpg12
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_01_30_07.jpg13
Figure 6-8 – 6420060018_SPSWIM_TO_16_51_2.75_0100_Cabinet_Exterior
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Figure 6-9 – 6420060018_SPSWIM_TO_16_51_2.75_0100_Power_Meter
_01_30_07.jpg14
Figure 6-10 – 6420060018_SPSWIM_TO_16_51_2.75_0100_Telephone_Box
_01_30_07.jpg14
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Figure 6-14 – 6420060018_SPSWIM_TO_16_51_2.75_0100_Trailing_WIM_Sensor
_01_30_07.jpg16
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_01_30_07.jpg17

MACTEC Ref. 6420060018\_2.75 2/15/2007 Page 3 of 17

### 1. General Information

SITE ID: 510100

LOCATION: US-29 Bypass, milepost 12.8, near Danville

VISIT DATE: January 30, 2007

VISIT TYPE: Validation

### 2. Contact Information

POINTS OF CONTACT:

Validation Team Leader: Dean J. Wolf, 301-210-5105, <a href="mailto:djwolf@mactec.com">djwolf@mactec.com</a>

Highway Agency: Mohamed Elfino, 804-328-3173,

Mohamed.elfino@vdot.virginia.gov

Richard Bush, 804-786-7006,

Richard.bush@vdot.virginia.gov

Hamlin Williams, 804-786-0134,

Hamlin.williams@vdot.virginia.gov

FHWA COTR: Debbie Walker, 202-493-3068, deborah.walker@fhwa.dot.gov

FHWA Division Office Liaison: Lorenzo Casanova, 804-775-3362, Lorenzo.casanove@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: <a href="http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm">http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm</a>

### 3. Agenda

BRIEFING DATE: *No briefing requested for this visit.* 

ON SITE PERIOD: January 30 through February 1, 2007.

TRUCK ROUTE CHECK: Completed at Calibration.

### 4. Site Location/ Directions

NEAREST AIRPORT: Piedmont Triad International Airport, Greensboro, NC

DIRECTIONS TO THE SITE: US-29 Bypass, approximately 8 miles north of Danville.

MEETING LOCATION: *On site beginning at 9:00 a.m.* 

WIM SITE LOCATION: US-29 bypass, milepost 12.8; GPS = 36.6599° N,

-79.3656° W.

WIM SITE LOCATION MAP: See Figure 4.1



Figure 4-1 – Site 510100 in Virginia

### 5. Truck Route Information

ROUTE RESTRICTIONS: None

SCALE LOCATION: 9181 US-29, Blairs, VA; approximately 4 miles north of the site;

 $GPS = 36.7163^{\circ} N$ ,  $-79.3793^{\circ} W$ .

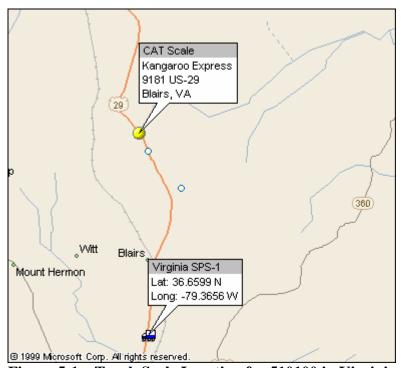


Figure 5-1 – Truck Scale Location for 510100 in Virginia

TRUCK ROUTE: See Figure 5.1

NB on US-29 to Blairs/Danville exit (2.7 miles) SB on US-29 to Halifax exit (3.1 miles)

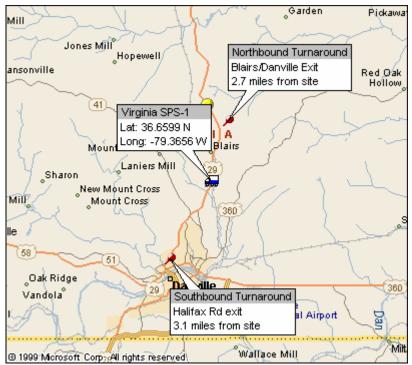


Figure 5-2 – Truck Route at 510100 in Virginia

SB distance = 3.1 miles NB distance = 2.7 miles

*Total distance* = 11.6 miles (14 minutes)

### 6. Sheet 17 – Virginia (510100)

1.* F	ROUTE _US-29	9 Bypass MILEPOST _	_12.8 LTPP DIR	ECTION - N S E W
2.* V	Nearest SPS	SCRIPTION - Grade _< section upstream of the si om sensor to nearest downs	te _5_1_0_1_4	_
3.* I	ANE CONFIC Lanes in LT	GURATION PP direction2_	Lane width	_1_2_ ft
	Median -	<ul> <li>1 – painted</li> <li>2 – physical barrier</li> <li>3 – grass</li> <li>4 – none</li> </ul>	Shoulder -	1 – curb and gutter  2 – paved AC  3 – paved PCC  4 – unpaved  5 – none
	Shoulder wi	dth1_1 ft		
4.* F	PAVEMENT T	YPEPCC		
Di Fi Di Fi 6. * 1	ate: 01/30/07 lename: 64200 ate: 01/30/07 lename: 64200 SENSOR SEQ REPLACEME	URFACE CONDITION – 60018_SPSWIM_TO_16_ 60018_SPSWIM_TO_16_ UENCELoop – E NT AND/OR GRINDING NT AND/OR GRINDING NT AND/OR GRINDING	51_2.75_0100_Ups 51_2.75_0100_Dov  Bending Plate – Ben	wnstream_01_30_07.jpg ding Plate – Loop
8. R.	Intersection distance Intersection distance	TERSECTIONS /driveway within 300 m up /driveway within 300 m do	ownstream of sensor	
9. I		Pending plate and load cell		<ul><li>1 - Open to ground</li><li>2 - Pipe to culvert</li><li>3 - None</li></ul>
		nder plate 4 . 0 ccess to flush fines from u		

Distance fr Distance fr	OCATION of road as LTPP lane <u>Y</u> / N Median Y/ <u>N</u> Behind barrier <u>Y</u> / N om edge of traveled lane _2_7 ft om system4_1 ft336 Short	
Cor	ACCESS controlled by LTPP / STATE / <u>JOINT</u> ?  ntact - name and phone number _Hamlin Williams804-786-7006_  ernate - name and phone numberRoy Czinku306-653-6627	
AC in cabi	o cabinet from drop4 ft Overhead / <u>underground</u> / solar net?  ovider Phone number	
	E cabinet from drop4 ft Overhead / <u>under ground</u> / cell? ovider Phone Number	
,	oftware & version no.)IRD iSINCconnection – <u>RS232</u> / Parallel port / USB / Other	
14. * TEST TRUC	CK TURNAROUND time14 minutesDistance _11.6 mi.	
15. PHOTOS	FILENAME	
(64200600	18_SPSWIM_TO_16_51_2.75_0100_)	
Power source	Power_Meter_01_30_07.jpg	
	Telephone_Box_01_30_07.jpg	
Cabinet exterior	Cabinet_Exterior_01_30_07.jpg	
	Cabinet_Interior_Front_01_30_07.jpg	
	Cabinet_Interior_Rear_01_30_07.jpg	
Weight sensorsLeading_WIM_Sensor_01_30_07.jpg		
Trailing_WIM_Sensor_01_30_07.jpg		
Other sensorsLeading_Loop_01_30_07.jpg		
	Trailing_Loop_01_30_07.jpg	
	oop Sensors	
	tion at sensors on LTPP lane: Downstream_01_30_07.jpg	
Upstream direction at sensors on LTPP lane:Upstream_01_30_07.jpg		

COMMENTS
concrete section = 425 feet
leading edge of leading loop is 313 feet from approaching transition
COMPLETED BYDean J. Wolf
PHONE 301-210-5105 DATE COMPLETED 0 1 / 3 0 / 2 0 0 7

#### Sketch of equipment layout

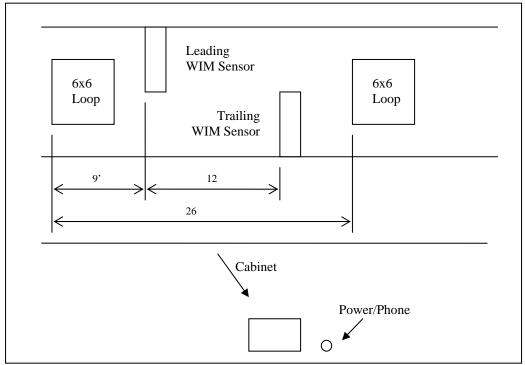


Figure 6-1 - Site Equipment Layout for 510100 in Virginia

### Site Map

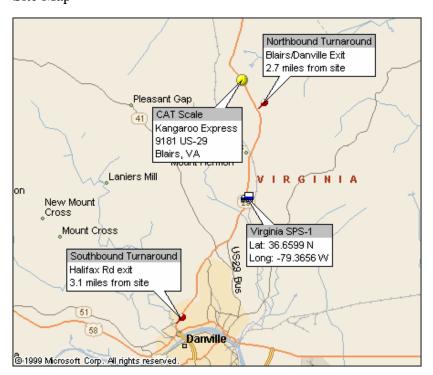


Figure 6-2 - Site Map for 510100 in Virginia



Figure 6-3 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Downstream \_01\_30\_07.jpg



Figure 6-4 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Upstream\_01\_30\_07.jpg



Figure 6-5 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Transition\_01\_30\_07.jpg



Figure 6-6 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Cabinet\_Interior\_Front \_01\_30\_07.jpg



Figure 6-7 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Cabinet\_Interior\_Rear \_01\_30\_07.jpg



Figure 6-8 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Cabinet\_Exterior \_01\_30\_07.jpg



Figure 6-9 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Power\_Meter \_01\_30\_07.jpg



Figure 6-10 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Telephone\_Box \_01\_30\_07.jpg



Figure 6-11 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Service\_Mast \_01\_30\_07.jpg



Figure 6-12 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Leading\_Loop \_01\_30\_07.jpg



Figure 6-13 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Leading\_WIM\_Sensor \_01\_30\_07.jpg



Figure 6-14 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Trailing\_WIM\_Sensor \_01\_30\_07.jpg



Figure 6-15 – 6420060018\_SPSWIM\_TO\_16\_51\_2.75\_0100\_Trailing\_Loop \_01\_30\_07.jpg

SHEET 18	STATE CODE	[_5_1_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0 ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_0_1_/_3_0_/_2_0_0_7_

1.		ATA PROCESSING —  Down load —  State only  LTPP read only  X LTPP download  LTPP download and copy to state
	b.	Data Review −  □ State per LTPP guidelines □ State − □ Weekly □ Twice a Month □ Monthly □ Quarterly X LTPP
	c.	Data submission – $\  \   \Box \   \text{State} - \Box \   \text{Weekly}  \Box  \text{Twice a month}  \Box   \text{Monthly}  \Box   \text{Quarterly} \\ X  LTPP$
2.	-	PUIPMENT – Purchase –  State X LTPP
	b.	Installation −  □ Included with purchase □ Separate contract by State □ State personnel X LTPP contract
	c.	Maintenance –  X Contract with purchase – Expiration Date8/2011_  □ Separate contract LTPP – Expiration Date  □ Separate contract State – Expiration Date  □ State personnel
	d.	Calibration −  □ Vendor  □ State  X LTPP
	e.	Manuals and software control – X State □ LTPP
	f.	Power –  i. Type –  Overhead X State  X Underground □ LTPP  Solar □ N/A

SHEET 18	STATE CODE	[_5_1_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0 ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_0_1_/_3_0_/_2_0_0_7_

	g.	$ \begin{array}{cccc} Communication - & & & \\ i. & Type - & & ii. & Payment - \\ & X \ Landline & & X \ State \\ & \Box \ Cellular & & \Box \ LTPP \\ & \Box \ Other & & \Box \ N/A \end{array} $
3.		AVEMENT – Type – X Portland Concrete Cement □ Asphalt Concrete
	b.	Allowable rehabilitation activities −  □ Always new □ Replacement as needed □ Grinding and maintenance as needed X Maintenance only □ No remediation
	c.	Profiling Site Markings –  □ Permanent  X Temporary
4.	ON a.	N SITE ACTIVITIES – WIM Validation Check - advance notice required2 □ days X weeks
	b.	Notice for straightedge and grinding check1 \( \square \) days X weeks i. On site lead - X State \( \subseteq \text{LTPP} \)
		<ul><li>ii. Accept grinding –</li><li>X State</li><li>□ LTPP</li></ul>
	c.	Authorization to calibrate site –  X State only  LTPP
	d.	Calibration Routine – $ \begin{array}{c} X \ LTPP - \square \ Semi\text{-annually} \ X \ Annually \\ \square \ State \ per \ LTPP \ protocol - \square \ Semi\text{-annually} \ \square \ Annually \\ \square \ State \ other -  \end{array} $

SHEET 18	STATE CODE	[_5_1_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0 ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_0_1_/_3_0_/_2_0_0_7_

5.

6.

e.	Test V i.	Vehicles Trucks –  1st – Air suspension 3S2  2nd –3S2  3rd – 4th –	☐ State ☐ State ☐ State ☐ State ☐ State	X LTPP X LTPP LTPP LTPP	
	ii.	Loads –	$\square$ State	X LTPP	
	iii.	Drivers –	$\square$ State	X LTPP	
f.	Contr	actor(s) with prior successful expe	rience in WIM	calibration in state:	
g.	Acces i.	ss to cabinet Personnel Access –  State only X Joint  LTPP			
	ii.	Physical Access −  X Key  □ Combination			
h.	State	personnel required on site –	X Yes □ No		
i.	Traffi	c Control Required –	□Yes X No		
j.	Enfor	cement Coordination Required –	□Yes X No		
SIT.		ECIFIC CONDITIONS – s and accountability –			
b.	Repor	ts –			
c.	Other				
d.	Specia	al Conditions –			
CONTACTS –					
a.	Equip	ment (operational status, access, e	tc.) –		
		Name: _Roy Czinku	Phone	: _306-653-6627	
		Agency:IRD/PAT Traffic			

SHEET 18	STATE CODE	[_5_1_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0 ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_0_1_/_3_0_/_2_0_0_7_

b.	Maintenance (equipment) –	
	Name: _Roy Czinku Phone: _306-653-6627	
	Agency:IRD/PAT Traffic	
c.	Data Processing and Pre-Visit Data –	
	Name: _Roy Czinku Phone: _306-653-6627	
	Agency:IRD/PAT Traffic	
d.	Construction schedule and verification –	
	Name:Don French Phone: _434-947-6559	
	Agency:Lynchburg District, VA DOT	
e.	Test Vehicles (trucks, loads, drivers) –	
	Name:Ed Foust Phone:434-799-6743	
	Agency:Thompson Trucking, Inc	
f.	Traffic Control –	
	Name:Don French Phone: _434-947-6559	
	Agency:Lynchburg District, VA DOT	
g.	Enforcement Coordination –	
	Name: Phone:	
	Agency:	
h.	Nearest Static Scale	
	Name:Kangaroo Location:I-29 Business, Blairs, VA	
	Phone:	

#### SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

\*STATE ASSIGNED ID [\_\_\_\_]
\*STATE CODE [\_5\_1\_]
\*SHRP SECTION ID [\_0\_1\_0\_0\_]

#### SITE CALIBRATION INFORMATION

1.	* DATE OF CALIBRATION (MONTH/DAY/YEAR) $[ _01/_3_0_/_2_0_0_7_]$
2.	* TYPE OF EQUIPMENT CALIBRATEDWIMCLASSIFIERx_BOTH
3.	* REASON FOR CALIBRATION  REGULARLY SCHEDULED SITE VISIT RESEARCH  EQUIPMENT REPLACEMENT TRAINING  DATA TRIGGERED SYSTEM REVISION NEW EQUIPMENT INSTALLATION _x_ OTHER (SPECIFY)LTPP Validation
4.	* SENSORS INSTALLED IN LTPP LANE AT THIS SITE (CHECK ALL THAT APPLY):  BARE ROUND PIEZO CERAMIC BARE FLAT PIEZO x_ BENDING PLATES  CHANNELIZED ROUND PIEZO LOAD CELLS QUARTZ PIEZO  CHANNELIZED FLAT PIEZO x_ INDUCTANCE LOOPS CAPACITANCE PADS  OTHER (SPECIFY)
5.	EQUIPMENT MANUFACTURERIRD/PAT Traffic
	WIM SYSTEM CALIBRATION SPECIFICS**
6.**	*CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N)x_ TEST TRUCKS
	NUMBER OF TRUCKS COMPARED2 NUMBER OF TEST TRUCKS USED
	2_1 PASSES PER TRUCK TRUCK TYPE SUSPENSION  TYPE PER FHWA 13 BIN SYSTEM 191  SUSPENSION: 1 - AIR; 2 - LEAF SPRING 292
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS A PERCENT)  MEAN DIFFERENCE BETWEEN  DYNAMIC AND STATIC GVW
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH) 45 , 55 , 65
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW SPEED)3_7_0_0
11.	** IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N)N IF YES, LIST AND DEFINE AUTO-CALIBRATION VALUE:

# CLASSIFIER TEST SPECIFICS\*\*\*

12.***	METHOD FOR COLLECTING INDEPENDENT V VIDEOx_ MANUAL	OLUME MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUN	T TIMEx_ NUMBER OF TRUCKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEHICLES:	FHWA CLASS
PERSON LEADING CALIBRATION EFFORT: _Dean J. Wolf, MACTEC Engineering rev. November 9, 1999		

#### SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

\*STATE ASSIGNED ID [\_\_\_\_]
\*STATE CODE [\_5\_1\_]
\*SHRP SECTION ID [\_0\_1\_0\_0\_]

#### SITE CALIBRATION INFORMATION

1.	* DATE OF CALIBRATION (MONTH/DAY/YEAR) [ _0_2_/_0_1_/_2_0_0_7_ ]
2.	* TYPE OF EQUIPMENT CALIBRATED WIM CLASSIFIERx_ BOTH
3.	* REASON FOR CALIBRATION  REGULARLY SCHEDULED SITE VISIT RESEARCH  EQUIPMENT REPLACEMENT TRAINING  DATA TRIGGERED SYSTEM REVISION NEW EQUIPMENT INSTALLATION _x_ OTHER (SPECIFY)LTPP Validation
4.	* SENSORS INSTALLED IN LTPP LANE AT THIS SITE (CHECK ALL THAT APPLY):  BARE ROUND PIEZO CERAMIC BARE FLAT PIEZO x_ BENDING PLATES  CHANNELIZED ROUND PIEZO LOAD CELLS QUARTZ PIEZO  CHANNELIZED FLAT PIEZO x_ INDUCTANCE LOOPS CAPACITANCE PADS  OTHER (SPECIFY)
5.	EQUIPMENT MANUFACTURERIRD/PAT Traffic
	WIM SYSTEM CALIBRATION SPECIFICS**
6.**	*CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N)x_ TEST TRUCKS  NUMBER OF TRUCKS COMPARED 2 NUMBER OF TEST TRUCKS USED
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS A PERCENT)  MEAN DIFFERENCE BETWEEN  DYNAMIC AND STATIC GVW0.8_ STANDARD DEVIATION2.7_  DYNAMIC AND STATIC SINGLE AXLES4.7_ STANDARD DEVIATION2.6_  DYNAMIC AND STATIC DOUBLE AXLES0.1_ STANDARD DEVIATION3.6_
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)45 , 55 , 65
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW SPEED)3_7_0_0
11.*	** IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N)N IF YES, LIST AND DEFINE AUTO-CALIBRATION VALUE:

## CLASSIFIER TEST SPECIFICS\*\*\*

12.***	METHOD FOR COLLECTING INDEPENDENT V VIDEO MANUAL	OLUME MEASUREMENT BY VEHICLE CLASS: PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT	T TIME NUMBER OF TRUCKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEHICL *** FHWA CLASS 9 *** FHWA CLASS 8	FHWA CLASS FHWA CLASS FHWA CLASS
	*** PERCENT "UNCLASSIFIED" VEHICLES: ON LEADING CALIBRATION EFFORT: _Dean J. V CACT INFORMATION:301-210-5105	Wolf, MACTEC Engineering rev. November 9, 1999



Sheet 19	* STATE_CODE	5 1
LTPP Traffic Data	* SPS PROJECT ID	0 1 0 0
*CALIBRATION TEST TRUCK # 1 Rev. 08/31/01	* DATE	01/30/2007
PART I.		
TAKI I.		
1.* FHWA Class 2.* Number of	Axles 5	
AXLES - units - lbs / 100s lbs / kg		
3. Empty Truck 4.* Pre-Test A	verage 5.* Post-Test Average	6.* Measured
Axle Weight Loaded Ax	kle Loaded Axle	D)irectly or
Weight A	Weight	C)alculated? D / C
		D, O
B		D / C
C	**************************************	D / C
D		D / C
	***************************************	<b>D</b> / C
E		D / C
F		D / C
GVW (same units as axles)		
	verage Pre-Test Loaded weight st Test Loaded Weight	
· ·	fference Post Test – Pre-test	
CEANTETON		
GEOMETRY		<i>y</i> m.,
8 a) * Tractor Cab Style - Cab Over Engine / Con	ventional b) * Sleeper Cab?	Y / (N)
9. a) * Make: <u>NTGANATIONAL</u> b) * Model: <u>900</u>	<u> </u>	
10.* Trailer Load Distribution Description:		
Wactor # 456 to. hr # 94		
1004		
	V-244-4-V/	THE STATE OF THE S
11. a) Tractor Tare Weight (units):		
(1. a) Hactor rate weight (units).		
b). Trailer Tare Weight (units):		

	THAN TECT TOHOV # 1	* 17 4 7777	0 3 / 2 0 / 2 0 /
Rev. 08/31/01	TION TEST TRUCK #_1	* DATE	01/30/20
12.* Axle Spacing – uni	ts m / feet and inches / t	feet and tenths	
A to B	B to C 4.9	C to D	
	D to E	E to F	
Wheelbased (mea	asured A to last)	Computed	
3. *Kingpin Offset From	m Axle B (units)	is to the rear)	
TIODERICIANI	. ( 7	is to the rear)	
USPENSION			
Axle 14. Tire Size	15.* Suspension Descrip	otion (leaf, air, no. of leaves, ta	aper or flat leaf, etc.)
A 11222.5	16.10	1 - %	
	- 100 lear	I talgered leat	
B <u>11222.5</u>		Italgered leaf	
	200		
B <u>11222.5</u>	2ir		
B <u>11622.5</u> C <u>11622.5</u>	3; c 3; c		
B <u>11822.5</u> C <u>11822.5</u> D 80824.5	air air		
B (1822.5 C 11822.5 D 80824.5 E 75824.5 F	dir dir		
B 11822.5 C 11822.5 D 80824.5 E 75824.5	dir dir		
B 1122.5 C 11222.5 D 80224.5 E 7524.5 F 6. Cold Tire Pressures (	dir dir		
B 1122.5 C 11222.5 D 80224.5 E 7524.5 F 6. Cold Tire Pressures (	psi) – from right to left		
B <u>11222.5</u> C 11222.5 D <u>802.24.5</u> E <u>75.24.5</u> F 6. Cold Tire Pressures (	psi) – from right to left		
B <u>11222.5</u> C 11222.5 D <u>802.24.5</u> E <u>75.24.5</u> F 6. Cold Tire Pressures (	psi) – from right to left  Axle C		

\* STATE CODE

\* SPS PROJECT ID

5 1

0 1 0 0

Sheet 19

LTPP Traffic Data

Sheet 19	* STATE_CODE	_5_1_
LTPP Traffic Data	* SPS PROJECT ID	0 1 0 0
*CALIBRATION TEST TRUCK #_1_	* DATE	0 1 / 3 0 / 2 0 0 7

Rev. 08/31/01

### PART II

Table 1. Axle and GVW computations - pre-test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW	
I	II	III	IV	V	V	
	-I	-II	-III	-IV		
V -VI	VI- VII	VII- VIII	VIII- IX	IX,	X	
					XI	
Avg.						

Table 2. Raw Axle and GVW measurements

Axles	Meas.	Pre-test Weight	Post-test Weight
A	I		
A + B	II		
A + B + C	III		
A + B + C + D	IV		
A + B + C + D + E (1)	V		
B+C+D+E	VI		
C + D + E	VII		
D+E	VIII		
Е	IX		
A + B + C + D + E (2)	X		
A + B + C + D + E (3)	XI		

Table 3. Axle and GVW computations - post -test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW	
I	п	III	IV	V	V	
	-I	-II	-III	-IV		
V	VI-	VII-	VIII-	IX,	X	
-VI	VII	VIII	IX			
					XI	
Avg.						

		Sheet 19				TE_CODE			5 1
		PP Traffic Data			····	PROJECT ID			0 1 0 0
LRev. 08/31/01		TON TEST TRU	CK #_1	*	* DAT	<u> </u>	1	0 1 / 3	0 / 2 0 0
		computations	-						
Axle A	Axle B	Axl	e C	Axle D		Axle E		GVW	7
	II	III		IV		V		V	
	-I	-II		-III		-IV			
V	VI-	VII-		VIII-		IX,		X	
VI	VII	VIII	-	IX					
								XI	
Avg.									
		scales – pre-te	1	pra					
Pass Pass	Axle A	Axle B	Axle C	Axle D		Axle E	Axle F	·	GVW
	10460	16710	16710	1606	20	16060	Wanterrossychen	,	<u>0000) F</u>
	10440	16720	16720	1605	50	16050	والمصور والإيادي والمصور		<u> 15980</u>
)	10460	16710	16710	1606	$\infty$	16060	Patrick Security		76000
Average	10450		16710	16060	0	16060	****		75990
my 1 post	10060	16620	16620	16060	0	16060	6,,		75420
able 6. Ra	w data – Axle	scales - dy	2 gre						
ass	Axle A	Axle B	Axle C	Axle D		Axle E	Axle F		GVW
	(0380	16710	16710	(6050		८७०५०	-AV galver		75400
	10400	16700	16700	16000		16060	,		75920
			W.C. 1 - C.	188842	<u>.</u>	G.			13100

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	(0380	16710	16710	(6050	16050	-ve	75400
2	10400	र १० १००	6070)	160060	16060	, 252-	75920
3	10400	6700	16.700	16060	16060	.episterini	75920
Average	10390	16700	(6700	16060	16060	man,	75920
de 2 aret	9880	16610	16610	16 n ser)	16050		79200

Table 7. Raw data - Axle scales - post-test day 3 fre

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	10380	16700	16700	16050	16050	V-constant	75880
2	10380	16690	16690	16050	16050	. Appellar.	75860
3	10380	16710	16710	16050	14050	уула	75900
Average	10380	16700	16700	12050	16050	Aur.	75500
dry 3005+	10160	16660	16660	16050	16020	eren.	75580

Measured By \_\_\_\_\_ Verified By \_\_\_\_\_

Shee		* STATE_CODE	5 1
LTPP Tra		* SPS PROJECT ID  * DATE	0 1 0 0
Rev. 08/31/01			**************************************
PART I.			
1.* FHWA Class	2.* Number of Axles	5	
AXLES - units - 1bs / 100s lb	s / kg		
3. Empty Truck Axle Weight	4.* Pre-Test Average Loaded Axle Weight	5.* Post-Test Average Loaded Axle Weight	6.* Measured D)irectly or C)alculated?
Α			D / C
В			D / C
C		***************************************	D / C
D			D / C
Е			D / C
F			D / C
GVW (same units as axles)			
7. a) Empty GVW	*c) Post Test	Pre-Test Loaded weight Loaded Weight Post Test – Pre-test	
GEOMETRY			
8 a) * Tractor Cab Style - Cab (	Over Engine / Convention	al b) * Sleeper Cab?	Y/D
9. a) * Make: International 1	o) * Model: 9900	WENT COST OF THE C	
10.* Trailer Load Distribution I	-		
LEVE			
11. a) Tractor Tare Weight (uni	ts):		
b). Trailer Tare Weight (uni	ts):		
6420060018_SPSWIM_TO_16	51 2.75 0100 Truck 2	Sheet 19 doc	

	Traffic Data	* SPS PROJECT ID	0 1 0 0
	N TEST TRUCK # 2	* DATE	01/30/2007
Rev. 08/31/01			
12.* Axle Spacing – units	m / feet and inches / fe	eet and tenths	
A to B	B to C4.3	C to D	
	D to E	E to F	
Wheelbased (measur	red A to last)	Computed	MARKATAN KATANIAN KA
13. *Kingpin Offset From A	xle B (units)	( + 3,0 )	
O <u>r</u>	(+i	(+3.0) s to the rear)	
SUSPENSION			
Axle 14. Tire Size  A \( \)(222.5)  B \( \)(222.5)  C \( \)(222.5)  D \( \)(222.5)  E \( \)(222.5)	1 fell less, 1 d  dir  air befored list, 1	tion (leaf, air, no. of leaves, t	
F			**************************************
16. Cold Tire Pressures (psi Steering Axle Axle	) – from right to left	Axle D	Axle E
	MANAGEMENT AND ADMINISTRATION OF THE PROPERTY	**************************************	**************************************
***************************************			
			Delinova and the second

\* STATE\_CODE \* SPS PROJECT ID

0 1 0 0

Sheet 19

LTPP Traffic Data

Sheet 19	* STATE CODE	5 1
LTPP Traffic Data	* SPS PROJECT ID	0 1 0 0
*CALIBRATION TEST TRUCK #_2_	* DATE	0 1 / 3 0 / 2 0 0 7

Rev. 08/31/01

## PART II

Table 1. Axle and GVW computations - pre-test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW
I	II	III	IV	V	V
	-I	-II	-III	-IV	
V -VI	VI- VII	VII- VIII	VIII- IX	IX,	X
					XI
Avg.					

Table 2. Raw Axle and GVW measurements

Axles	Meas.	Pre-test Weight	Post-test Weight	
A	I			
A + B	II			
A + B + C	ın			
A + B + C + D	IV			
A + B + C + D + E (1)	V			
B+C+D+E	VI			
C + D + E	VII			
D + E	VIII			
Е	IX			
A + B + C + D + E (2)	X			
A + B + C + D + E(3)	XI			

Table 3. Axle and GVW computations - post -test

Axle A	Axle B	Axle C	Axle D	Axle E	GVW
I	П	m	IV	V	V
	-I	-II	-III	-IV	
V	VI-	VII-	VIII-	IX,	X
-VI	VII	VIII	IX		
					XI
Avg.					

		Sheet 19			* STATE_CODE				
	······································	PP Traffic Data	Cate II A		PROJECT ID		0 1 0 0		
L		ION TEST TRU	CK # 2	* DA	IE	U I /	3 0 / 2 0 0 7		
	axle and GVW	computations	<del>-</del>						
Axle A	Axle B	Axle	e C	Axle D	Axle E	GV	W		
- Company of the Comp	II	III		IV	V	V			
	<b>-</b> I	-II		-III	-IV				
V	VI-	VII-		VIII-	IX.	X	000000000000000000000000000000000000000		
·VI	VII	VIII		IX					
						XI			
Avg.									
Γable 5. Ra	aw data – Axle Axle A	Axle B	Axle C		Axle E	Axle F	GVW		
	11120	1310 V42040	XXXE4910	13480	13480	44,000,000,000	65500		
,			1300 C	ASHOE	HASANGAS/	VAAAN	65500		
3	Illoo	VAVERAO	YARMO	13580	13580	Commentation of the second	65520		
Average	11040	13040	13690	13,530	19.530	*Vicabellogge	655 <b>40</b>		
my 1 post	- 10760	13310	(3310	13760	1)760	out before.	64900		
Table 6. Ra	aw data – Axle	scales – તા	2 812						
) <sub>aee</sub>	Δvle Δ	Avle R	AvleC	AvlaD	Avle F	AvleE	GVW		

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	14-3-46-44 B	13680	13680	(3500	13500		65480
2	1020	13280	13280	13940	13940	يارين	65460
3	10-100	13700	13700	13450	13480		65460
Average	11080	13550	13550	13640	13640		45 470
day 2 post	10620	13360	13360	13680	13680	gav.	64700

Table 7. Raw data – Axle scales – post-test , 3

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11300	13400	13400	13710	13710	_	62250
2	11160	13480	13480	13700	13700	.,,,,,,,	65520
3	11160	13470	13470	13700	13700	have	65500
Average	11210	13450	13450	13700	13700	,044s.	45510
day 3 post	10940	13430	13430	13 680	13680		65160

Measured By Verified By

		Sheet 20		* STATE	E CODE	, , , , , , , , , , , , , , , , , , , ,		5 1	
		TPP Traffic l			*SPS PR	OJECT_	ID		0_1_0_0
		ication Chec	ks * /	of* 2_	* DATE		0_1_/	3_0_/_2	0 0 7
WIM	31/2001   WIM	WIM	01-	T 01	I 77778 4	TTTTS	TTTT		
speed	class	Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
, I, 4 4 4	01000	100010	Speed	Ciass	speed	Ciass	RCCOId	Speed	Class
Co	ଦ୍ୱ	48915	60	O <sub>q</sub>	72	sq	49103	סד	\$
64	8	48016		£**	60	5			
	554	48925	_				49110	62 (	65
65	4			9	63	<u></u>	49113	<u>62</u>	9
403	<u> </u>	46925		<u> </u>	59	57	49116	25	9
44	4	48936	44	44.9	60	9	49120	60	9
45	9	48937	45	9	65	5	49156	65	
59	9	48969	60	<u> </u>	57	<u> </u>	49161	<u></u>	5
70	9	48998	71	9	٥2	6	49172	63	6
62	6	49003	62	L6_	ر حا	9	49200	67	9
SA	9	49019	29		59	()	49201	58	11
<b>66</b>	9	49032	64_	9	<u> </u>	ري.	4-912-11	58	<u></u>
60	3	49035	59	9	57	e <sub>1</sub>	49217	57	٩
68	9	49043	65	9	<b>6</b> 1	9]	mag	Gl	9
62	9	49046	61	9	<b>45</b>	9	49223	65	84
48	6	49049	48	6	60	e <sub>1</sub>	49224	(gr	9
60	9	49050	6)	3	62	9	49227	62	q
6D	5	4-9055	60	5	65	9	49233	65	<u></u>
60	3	49000	64	9	60	9	49234	60	9
<u>68</u>	9	49081	68	47	64	ප		64	8
<u> </u>	9	49082	GG	9	64		49239	64	
64	5	49087	64	9	<u> </u>	9	49240	55	9
58	9	49088	82	9	کی ۔	9	49249	64	جي رجي
60	5	49090	62	S	58	5	49283	·57	5
67	9	49096	67	9	යින	6	49284	<b>69</b>	9
65	6,	49098	64	6	58	9	49292	56	9)
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SHEET 22 LTPP MONITORED TRAFFIC DATA	* STATE CODE [_5_1_] * SPS PROJECT ID [_0_1_0_0_]
SITE EQUIPMENT ASSESSMENT	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) _0_1_ / _3_0_ / _2_0_0_7_

# SITE EQUIPMENT INFORMATION

TYPE OF EQUIPMENT WIM VCx_BOTH	
LANE NUMBER ON-SITE1 DIRECTION ON-SITESouth	
VENDORIRD MODEL _iSINC SERIAL NO060703525	
WEIGHING SENSOR TYPEBending Plate_	
SYSTEM SOFTWARE VERSIONS:	
LOOP	
PIEZO	
WEIGHPAD/ LOAD CELL	
COMMUNICATION	
CLASSIFICATION VIDEO:	
TIME FROM: TO:	
SITE CONDITIONS	
PAVEMENT:	
INDICATE ANY DEFICIENCIES THAT MAY AFFECT THE PERFORMANCE OF TH SYSTEM. LIST ALL PHOTOS THAT SUPPORT THE EVALUATION.	E WIM
None	
Assessor:Dean J. Wolf Page 1 of 8 Rev. 11/12/2003	

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SHEET 22 LTPP MONITORED TRAFFIC DATA	* STATE CODE [_5_1_] * SPS PROJECT ID [_0_1_0_0_]
SITE EQUIPMENT ASSESSMENT	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_

OAD GENGODG		
OAD SENSORS:		
SENSORS THAT SHOW A	NCIES REGARDING THE SENSOR IN NY SIGN OF BEING BROKEN, SEVER IST PHOTOS FOR EACH OCCURANC	RELY WORN, MISSING
None		
	TRUCK OBSERVATIONS	
	LAR TRUCK BEHAVIORS SUCH AS B WEIGHING AREA (WITHIN 40 METE EIGHING SENSORS.	
OR BRAKING NEAR THE	WEIGHING AREA (WITHIN 40 METE	
OR BRAKING NEAR THE DISTANCE FROM THE W	WEIGHING AREA (WITHIN 40 METE	
OR BRAKING NEAR THE DISTANCE FROM THE W	WEIGHING AREA (WITHIN 40 METE	
OR BRAKING NEAR THE DISTANCE FROM THE W	WEIGHING AREA (WITHIN 40 METE	
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OR BRAKING NEAR THE DISTANCE FROM THE W	WEIGHING AREA (WITHIN 40 METE	
OR BRAKING NEAR THE DISTANCE FROM THE W	WEIGHING AREA (WITHIN 40 METE	
OR BRAKING NEAR THE DISTANCE FROM THE WINDOWN	WEIGHING AREA (WITHIN 40 METE EIGHING SENSORS.  R 35 TRUCK SAMPLE VIDEO FOR PA	ERS). NOTE THE

Assessor: \_\_Dean J. Wolf\_\_\_ Rev. 11/12/2003

Page 2 of 8

SHEET 22 LTPP MONITORED TRAFFIC DATA	* STATE CODE [_5_1_] * SPS PROJECT ID [_0_1_0_0_]
SITE EQUIPMENT ASSESSMENT	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_

#### CLASSIFICATION VERIFICATION VIDEO:

TAPE 1- NAME:			
Interval 1 – FILE:		TO:	
Interval 2 – FILE:	TIME FROM:	TO:	
Interval 3 – FILE:	TIME FROM:	TO:	
Interval 4 – FILE:	TIME FROM:	TO:	
Interval 5 – FILE:	TIME FROM:	TO:	
Interval 6 – FILE:	TIME FROM:	TO:	
Interval 7 – FILE:	TIME FROM:	TO:	
TAPE 2- NAME:			
Interval 1 – FILE:	TIME FROM:	TO:	
Interval 2 – FILE:	TIME FROM:	TO:	
Interval 3 – FILE:	TIME FROM:	TO:	
Interval 4 – FILE:	TIME FROM:	TO:	
Interval 5 – FILE:	TIME FROM:	TO:	
Interval 6 – FILE:	TIME FROM:	TO:	
Interval 7 – FILE:	TIME FROM:	TO:	
TAPE 3- NAME:			
Interval 1 – FILE:	TIME FROM:	TO:	
Interval 2 – FILE:	TIME FROM:	TO:	
Interval 3 – FILE:	TIME FROM:	TO:	
Interval 4 – FILE:	TIME FROM:	TO:	
Interval 5 – FILE:	TIME FROM:	TO:	
Interval 6 – FILE:	TIME FROM:	TO:	
Interval 7 – FILE:	TIME FROM:	TO:	

Assessor:	Dean J.	Wolf	
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SHEET 22 LTPP MONITORED TRAFFIC DATA	* STATE CODE [_5_1_] * SPS PROJECT ID [_0_1_0_0_]
SITE EQUIPMENT ASSESSMENT	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_

# SYSTEM ACCURACY TESTS

ED AND CLASSIFICATION – CO AVERAGE DISTANCE BETW				FT/ m
% ERROR FROM (from sy	stem record average	e) FEET		% ERROR
SPEED ACCURACY mea	an difference	SD of	mean	
****	Validation – see res	sults*****		
GHT – COMPLETE SHEET 21 A	ND ATTACH			
AVERAGE FRONT AXLE WE	IGHT FOR CLASS	9 VEHICLES		LBS/kg
% ERROR FROM 10,300/	(known	site value) LB	S	
SUPPO	RT EQUIPMENT/S	STRUCTURES	<u>.</u>	
INDICATE ANY DEFICIENCI ROAD SENSORS. LIST PHOT	ES WITH ANY SIT	ΓΕ EQUIPMEN CURANCE.	•	HAN THE IN-
INDICATE ANY DEFICIENCI	ES WITH ANY SIT	ΓΕ EQUIPMEN CURANCE.	•	HAN THE IN-
INDICATE ANY DEFICIENCI ROAD SENSORS. LIST PHOT	ES WITH ANY SIT	ΓΕ EQUIPMEN CURANCE.	•	HAN THE IN-
INDICATE ANY DEFICIENCI ROAD SENSORS. LIST PHOT	ES WITH ANY SIT	TE EQUIPMEN CURANCE. x	•	HAN THE IN-
INDICATE ANY DEFICIENCI ROAD SENSORS. LIST PHOT CABINET/FOUNDATION	ES WITH ANY SIT	TE EQUIPMEN CURANCE. x	•	HAN THE IN-

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* STATE ASSIGNED ID []  * DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_
* DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_
NONE _N/A_
NONEx
NONE _x_
NONEe another in cabinet
NONEx

Assessor: \_\_Dean J. Wolf\_\_\_ Rev. 11/12/2003

SHEET 22 LTPP MONITORED TRAFFIC DATA	* STATE CODE [_5_1_] * SPS PROJECT ID [_0_1_0_0_]	
SITE EQUIPMENT ASSESSMENT	* STATE ASSIGNED ID []	
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_	

## STATIC EQUIPMENT VALUES (SYSTEM OFF)

POWER	-			<del></del>	
SOLAR PANEL	WA	TTS	VDC		
AC	_120.7 _ VA	C			
BATTERY 1	_13.6 VD	C			
BATTERY 2	VD	C			
REGULATED	VD	C			
POWER SUPPLY	_11.8 VD	C			
SYSTEM INPUT	_120.7 _ VD	C			
MODEM POWER	_120.7 _ VA	C	VDC		
TELEPHONE	_51.4 VD	C			
LOOP SENSORS					
L1 (LEAD)	RES7	_Ω; IND	Uh; S	SHLD14	$_{ m M}\Omega$
L2 (TRAIL)	RES6	_Ω; IND	Uh; S	SHLD14	_MΩ
WEIGHPAD SENSORS					
WP1 (LEAD)	INPUT97	<sup>7</sup> 2 <u>Ω</u> ; OUT	PUT847	Ω; SHLD	inf MΩ
WP2 (TRAIL)	INPUT97	$^{73}$ $\Omega$ ; OUT	PUT847	_Ω; SHLD	inf MΩ
PIEZO SENSORS					
PZ1 (LEAD)	RES	_Ω; CAP	Nf		
PZ2	RES	_Ω; CAP	Nf		
PZ3	RES	_Ω; CAP	Nf		
PZ4 (TRAIL)	RES	_Ω; CAP	Nf		
LOAD CELL SENSORS					
LC1 (LEAD)	INPUT	Ω; OUTP	UT	_Ω; SHLD _	ΜΩ
LC2 (TRAIL)	INPUT	Ω; OUTP	UT	_Ω; SHLD _	ΜΩ
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SHEET 22 LTPP MONITORED TRAFFIC DATA	* STATE CODE [_5_1_] * SPS PROJECT ID [_0_1_0_0_]
SITE EQUIPMENT ASSESSMENT	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_

#### KISTLER SENSORS

RES  $\Omega$ ; CAP Nf K1 (LEAD L) RES  $\_$   $\Omega$ ; CAP  $\_$  Nf K2 (LEAD ML) RES  $\Omega$ ; CAP Nf K3 (LEAD MR) RES  $\Omega$ ; CAP Nf K4 (LEAD R) RES  $\Omega$ ; CAP Nf K5 (TRAIL L) RES  $\_$   $\Omega$ ; CAP  $\_$  Nf K6 (TRAIL ML) RES  $\_$   $\Omega$ ; CAP  $\_$  Nf K7 (TRAIL MR) RES  $\_$   $\Omega$ ; CAP  $\_$  Nf K8 (TRAIL R)

#### DYNAMIC EQUIPMENT VALUES (SYSTEM ON)

#### **LOOP SENSORS**

L1 (LEAD) FREQ \_\_12.4 \_ KHz;

L2 (TRAIL) FREQ \_\_12.4 \_ KHz

#### WEIGHPAD SENSORS

WP1 (LEAD) ZERO POINT \_0.0 \_\_\_ Mv

WP2 (TRAIL) ZERO POINT \_0.1 \_\_\_ Mv

#### PIEZO SENSORS

PZ1 (LEAD) AMPLITUDE (CLASS 9) \_\_\_\_\_ Mv

PZ2 AMPLITUDE (CLASS 9) \_\_\_\_\_ Mv

PZ3 AMPLITUDE (CLASS 9) \_\_\_\_\_ Mv

PZ4 (TRAIL) AMPLITUDE (CLASS 9) \_\_\_\_\_ Mv

#### LOAD CELL SENSORS

LC1 (LEAD) ZERO POINT \_\_\_\_\_ Mv
LC2 (TRAIL) ZERO POINT \_\_\_\_ Mv

Assessor: \_\_Dean J. Wolf\_\_\_\_\_

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SHEET 22 LTPP MONITORED TRAFFIC DATA	* STATE CODE [_5_1_] * SPS PROJECT ID [_0_1_0_0_]
SITE EQUIPMENT ASSESSMENT	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) _0_1_/_3_0_/_2_0_0_7_

# ADDITIONAL COMMENTS

- trucks bouncing at transition 313' prior to site
- amenities are located in Danville, approximately 8 miles south of site
- weighscales at CAT Scales (BP Gas Station, Kangaroo Express). Approximately 4 miles north of site
- lane 1 – low GVW for Truck 1 at 55 mph

Assessor: \_\_Dean J. Wolf\_\_\_\_\_\_ Rev. 11/12/2003 Page 8 of 8

SHEET 23	* STATE CODE [51]
LTPP MONITORED TRAFFIC DATA	* SPS PROJECT ID [0 0 0]
WIM SYSTEM TROUBLESHOOTING OUTLINE	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) 0 1 / 3 1 / 20 0 7
PROBLEM REPORT DATE: 1/2/07 TIME:  SITE # 510100  LANE # 1/2 LANE DIRECTION	
STEP 1 – PROBLEM DESCRIPTION	
PROVIDE A DETAILED DESCRIPTION OF THE	PROBLEM.
When tenters, trucks of high tailers a	skeleton tailers first, the loops
Kick off under the failer couring esta	rs is the records
STEP 2 – COLLECT SYSTEM DATA	
2A – SYSTEM PARAMETERS	
REVIEW ALL EQUIPMENT OPERATIONAL PARALGORITHMS, DATE/TIME, WEIGHT AND SPE FACTORS, AS WELL AS SENSOR LANE ASSIGN	ED/SPACING ERROR COMPENSATION
MAKE NOTE OF ANY SUSPECT VALUES. DO	NOT CHANGE ANY VALUES AT THIS TIME.

Page 1 of 5

SHEET 23	* STATE CODE [ <u>5</u> ]
LTPP MONITORED TRAFFIC DATA	* SPS PROJECT ID [OLOO]
WIM SYSTEM TROUBLESHOOTING OUTLINE	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) 0 1 / 3 / / 20 27

#### 2B – DOWNLOAD SYSTEM DATA

DOWNLOAD SYSTEM TRAFFIC DATA FOR THE DAY OR TIME PERIOD IN QUESTION. SITE PROBLEMS THAT CAN ONLY BE DETERMINED BY REVIEWING DATA FILES WILL MOST LIKELY REQUIRE A SECOND VISIT UNLESS THE FILES CAN BE PROCESSED ON SITE.

#### 2C - RECORD SYSTEM DIAGNOSTIC MODE VALUES

RECORD ALL SENSOR VALUES GIVEN IN THE SYSTEMS' DIAGNOSTIC MODE FOR THE LANE BEING INVESTIGATED IF AVAILABLE. MAKE NOTE OF ANY DEFICIENCIES OR SUSPECT OR INCONSISTENT VALUES.

SUSPECT OR	INCONSIST	TENT VALU
LOOP SENSO	PRS	
LOOP	VALUE	
LEADING		
TRAILING		·
WEIGHPAD/I	LOAD CELL	SENSORS
SENSOR	VALUE	
LEADING		
TRAILING		
PIEZO SENSO	ORS	
PIEZO	VALUE	
LEADING		
2 <sup>nd</sup>		
3 <sup>rd</sup>		
TRAILING		
KISTLER QU.	ARTZ SENS	ORS
SENSOR.	VALUE	
LEADING		
TRAILING		
Assessor:	Ju	

SHEET 23	* STATE CODE [5]
LTPP MONITORED TRAFFIC DATA	* SPS PROJECT ID [ <u>@ L @ o</u> ]
WIM SYSTEM TROUBLESHOOTING OUTLINE	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) <u>5 ( / 3 ( / 2×5 )</u>

TEMPERATURE	
<u> </u>	
NOTES:	
long frequencies are all the same for each law	«
(dre 1 = 12 km 3	
lue 2 = 10 KG3	
all loops ned 14M to grant	
STEP 3 – FINDING THE SOURCE OF THE PROBLEM	
3A – PROBABLE FAULTY FUNCTION	
LIST THE DEFICIENCIES DISCOVERED IN STEPS 1 & 2 BELOW. ASSOCIATED WIM SYSTEM PRIMARY FUNCTIONS (POWER, CO. & CLASSIFICATION, EC.)	
SYMPTOM	FUNCTION
loves dop out	closs 2 weighing
BASED ON THE SYMPTOMS LISTED ABOVE, MAKE A CONCLUPROBABLE FAULTY SYSTEM FUNCTION. ADD ANY CLARIFYI	
PROBABLE FAULTY FUNCTION	
class a weighing	
Assessor:	Page 3 of 5

SHEET 23	* STATE CODE	[5]
LTPP MONITORED TRAFFIC DATA	* SPS PROJECT ID	[0109]
WIM SYSTEM TROUBLESHOOTING OUTLINE	* STATE ASSIGNED ID	[]
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) 0 1 / 3 t / 2 s o つ	

#### 3B – FAULTY COMPONENT

USE THE STANDARD EQUIPMENT MAINTENANCE FORM (SHEET 22) TO RECORD ALL SYSTEM COMP[ONENT STATIC AND DYNAMIC VALUES USING THE TEST POINTS INDICATED BELOW FOR THE SYSTEM FUNCTION IN QUESTION.

TP#	TEST POINT DESCRIPTION S	YSTEM FUNCTION
1	WIM SYSTEM POWER INPUT	POWER
2	DC MODEM INPUT	POWER/ COMMUNICATION
3	TEL SURGE SUPPRESSOR OUTPUT	COMMUNICATION
4	TEL TERMINAL STRIP OUTPUT	COMMUNICATION
5	TEL D-MARK BOX OUTPUT	COMMUNICATION
6	SENSOR TERMINAL STRIP INPUTS	CLASSIFICATION AND WEIGHING
7	PULL BOX INPUTS	CLASSIFICATION AND WEIGHING
8	DC POWER TERMINAL STRIP OUTPUTS	POWER
9	DC REGULATOR OUTPUT	POWER
10	BATTERY OUTPUT	POWER
11	SOLAR SURGE SUPPRESSOR OUPUT	POWER
12	SOLAR PANEL OUPUT	POWER
13	AC POWER TERMINAL STRIP	POWER
14	AC SERVICE DROP OUTPUT	POWER
15	AC CIRCUIT BREAKER OUTPUT	POWER
16	AC OUTLET OUTPUT	POWER
17	EXTERNAL POWER SUPPLY OUTPUT	POWER

BASED ON THE TEST READINGS MADE, DRAW A CONCLUSION AS TO THE MOST PROBABLE FAULTY COMPONENT AND INDICATE BELOW.

FAULT	Y COM	PONEN	Т	
	100 p s	( Yesl	(ni-	
	7		· · · · · · · · · · · · · · · · · · ·	
Assessor:		DW		

SHEET 23	* STATE CODE [5_1]
LTPP MONITORED TRAFFIC DATA	* SPS PROJECT ID [OLO ]
WIM SYSTEM TROUBLESHOOTING OUTLINE	* STATE ASSIGNED ID []
LTPP LANE ONLY	* DATE: (mm/dd/yyyy) <u>0 1 / 3 1 / 2 0 0 7</u>

### STEP 4 – DETERMINE THE CORRECTIVE ACTION

CONSIDERING ALL FACTORS ASSOCIATED WITH THE REPAIR OF THE FAULTY COMPONENT, DETERMINE THE CORRECTIVE ACTION.

DESRIBE THE CORRECTIVE ACTIONS TAKEN BELOW.
replace loop input wines w/ shielded 2 conductor lead-i- cuble from pell box to termination
STEP 5 – REPAIRING THE SYSTEM
DESCRIBE THE ACTIONS TAKEN TO REPAIR THE SYSTEM, OR MAKE RECOMMENDATIONS ON THE REPAIRS THAT NEED TO BE TAKEN TO CORRECT THE SYSTEM DEFICIENCY.
regarded to b. My us 2/ IRO

Assessor:	USW
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#### System Operating Parameters

Virginia SPS-1 (Lane 1)

Validation Visit – 30 January, 2007

#### Calibration factor for sensor #1:

72 kph:	3700
88 kph:	3700
105 kph:	3700
121 kph:	3700
137 kph:	3700

#### Calibration factor for sensor #2:

72 kph:	3700
88 kph:	3700
105 kph:	3700
121 kph:	3700
137 kph:	3700

# ETG LTPP CLASS SCHEME, MOD 3

13	-	13	12	ļ	ļ	-	-				ω u			7			ļ. 	-	6	ļ	4	(J.)	2	S	_						
9 Axle Multi's		7 Axle Multi's	Semi+Full Trailer, 3S12	Semi, 3S3	Semi+FullTrailer, 2812	Sem1, 2S3	Truck+Full Trailer (3-2)	Semi, 3S2	5 Axle Single Unit	2D w/3 Axle Trailer	Other w/3 Axle Trailer	Semi, 2S2	Semi, 3SI	4 Axle Single Unit	2D w/2 Axle Trailer	Other w/2 Axle Trailer	Car w/2 Axle Trailer	Semi, 2S1	3 Axle Single Unit	2D w/ 1 Axle Trailer	Bus	Other w/ I Axle Trailer	Car w/ 1 Axle Trailer	2D Single Unit	Bus	Other (Pickup/Van)	Passenger Car	Motorcycle	Office Agency Control of the Control		
9	80	7	6	6	J	5	5	'n	Un	5	J.	4	4	4	4	4	4	3	cu	သ	w	w	w	2	2	2	2	2		Axles	
6.00-45.00	6.00-45.00	6.00-45.00	6.00-26.00	6.00-26.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-30.00	6.00-23.09	6.00-23.09	10.11-23.09	6.00-26.00	6.00-26.00	6.00-23.09	6.00-26.00	10.11-23.09	6.00-10.10	6.00-23.09	6.00-23.09	6.00-23.09	23.10-40.00	10.11-23.09	6.00-10.10	6.00-23.09	23.10-40.00	10.11-23.09	6.00-10.10	1.00-5.99			T Surving
3.00-45.00	3.00-45.00	3.00-45.00	2.50-6.30	2.50-6.30	11.00-26.00	16.00-45.00	2.50-6.29	2.50-6.29	2.50-6.29	6.30-35.00	6.00-25.00	8.00-45.00	2.50-6.29	2.50-6.29	6.30-40.00	6.00-30.00	6.00-30.00	11.00-45.00	2.50-6.29	6.30-30.00	3.00-7.00	6.00-25.00	6.00-25.00								Surviva &
3.00-45.00	3.00-45.00	3.00-45.00	11.00-26.00	6.10-50.00	6.00-20.00	2.50-6.30	6.30-50.00	6.30-65.00	2.50-6.29	1.00-25.00	1.00-11.99	2.50-20.00	13.00-50.00	2.50-12.99	1.00-20.00	1.00-11.99	1.00-11.99									,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,					c Survedo
3.00-45.00	3.00-45.00	3.00-45.00	6.00-24.00	2.50-11.99	11.00-26.00	2.50-6.30	12.00-27.00	2.50-11.99	2.50-6.30	1.00-11.99	1.00-11.99																				e Surredo
3.00-45.00	3.00-45.00	3.00-45.00	11.00-26.00	2.50-10.99		****							***************************************																		c Surredc
3.00-45.00	3.00-45.00	3.00-45.00																													o Surpade
3.00-45.00	3.00-45.00											100 pt		and the second		77700							and a second								Spacing /
3.00-45.00																															Spacing 8
20.00>	20.00>	20.00>	20.00 >	20.00>	20.00>	20.00 >	20.00>	20.00 >	12.00 >	12.00-19.99	1.00-11.99	20.00>	20.00 >	12.00>	12.00-19.99	1.00-11.99	1.00-11.99	20.00 >	12.00 >	12.00-19.99	20.00 >	-1.00-11.99	1.00-11.99	8.00>	12.00 >	1.00-7.99	1.00-7.99	0.10-3.00		Weight Min-Max	Gross
5.0	5.0	5.0	5.0	5.0	3.5	3.5	3.5	5.0	3.5	2.5		3.5	5.0	3.5	2.5		***************************************	3.5	3.5	2.5				2.5						Weight Min *	Axle

Spacings in feet
Weights in kips (Lbs/1000)
\* Suggested Axle 1 minimum weight threshold if allowed by WIM system's class algorithm programming

# TEST TRUCK PHOTOS FOR SPS WIM FIELD VALIDATION

**STATE: Virginia** 

**SHRP ID: 510100** 

# Figures

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